



A G-Polygon Based Spatial Prescreening Technique and Its Application to AIRS Data

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Introduction

- Why prescreening?
- G-polygon vs bounding box
- An accurate prescreening technique
- Its applications to AIRS data

The technique is described in [A Spatial Pre-Screening Technique for Earth Observation Data](#), IEEE Geoscience and Remote Sensing Letters, Vol. 4, No. 1, January 2007

by Xin-Min Hua, Jianfu Pan, Dimitar Ouzounov, Alecei Lyapustin, Yujie Wang, Krishna Tewari, Gregory Leptoukh and Bruce Vollmer,



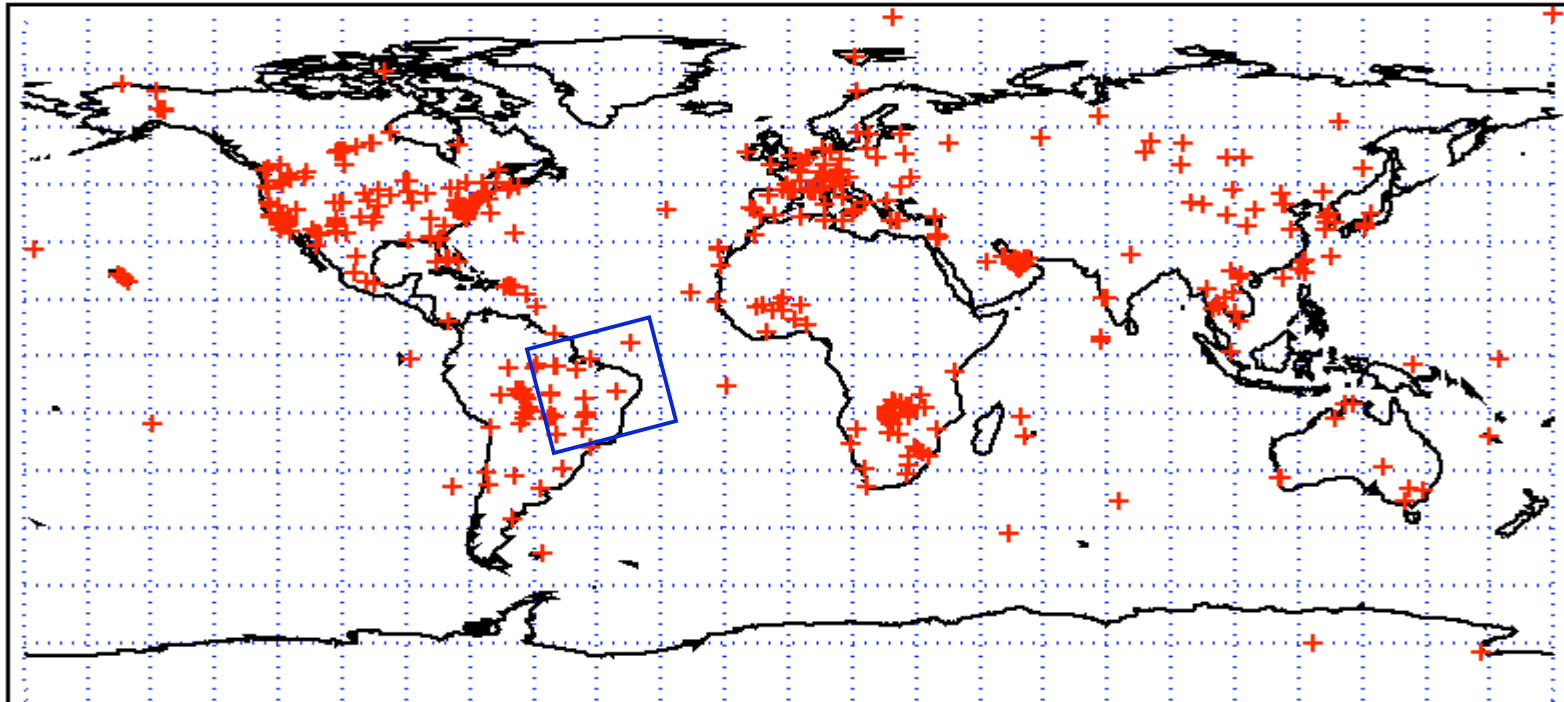
Why prescreening?

- EOS instruments (MODIS, AIRS) provide data granules covering large spatial areas, on the order of 1000 km.
- Many researches (e.g. comparative studies, validation by ground observations) focus on regional processes, requiring much less than full granules.
- Researchers want to know in advance if a given data granule covers the locations of interest to them.



An example: AERONET stations

Aeronet Stations



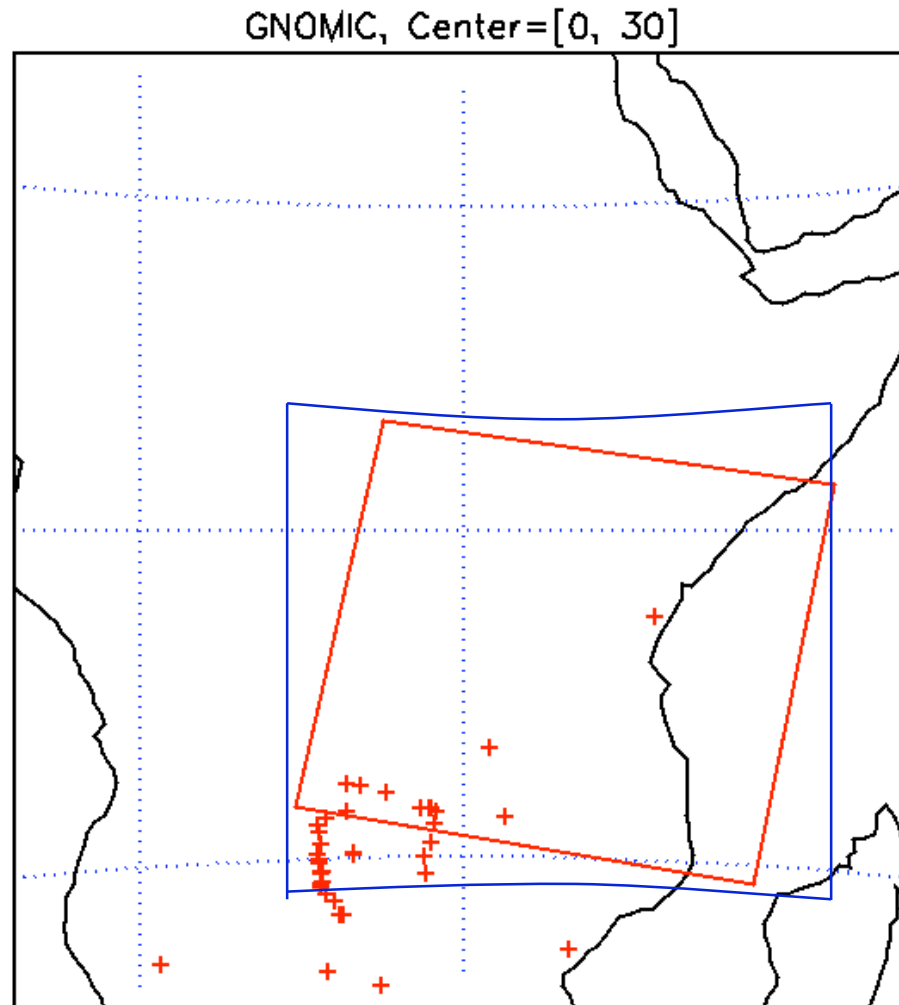


Options

- No pre-screening: pixel-by-pixel comparison – slow.
- Bounding box (Max./Min. lat/lon) – inaccurate, needs special treatment for high-latitude and dateline/pole crossing granules.
- An accurate prescreening algorithm, capable of handling all data granules uniformly, regardless of their locations on the Earth, with no special treatment required for dateline/pole crossing granules. – Too good to be possible?



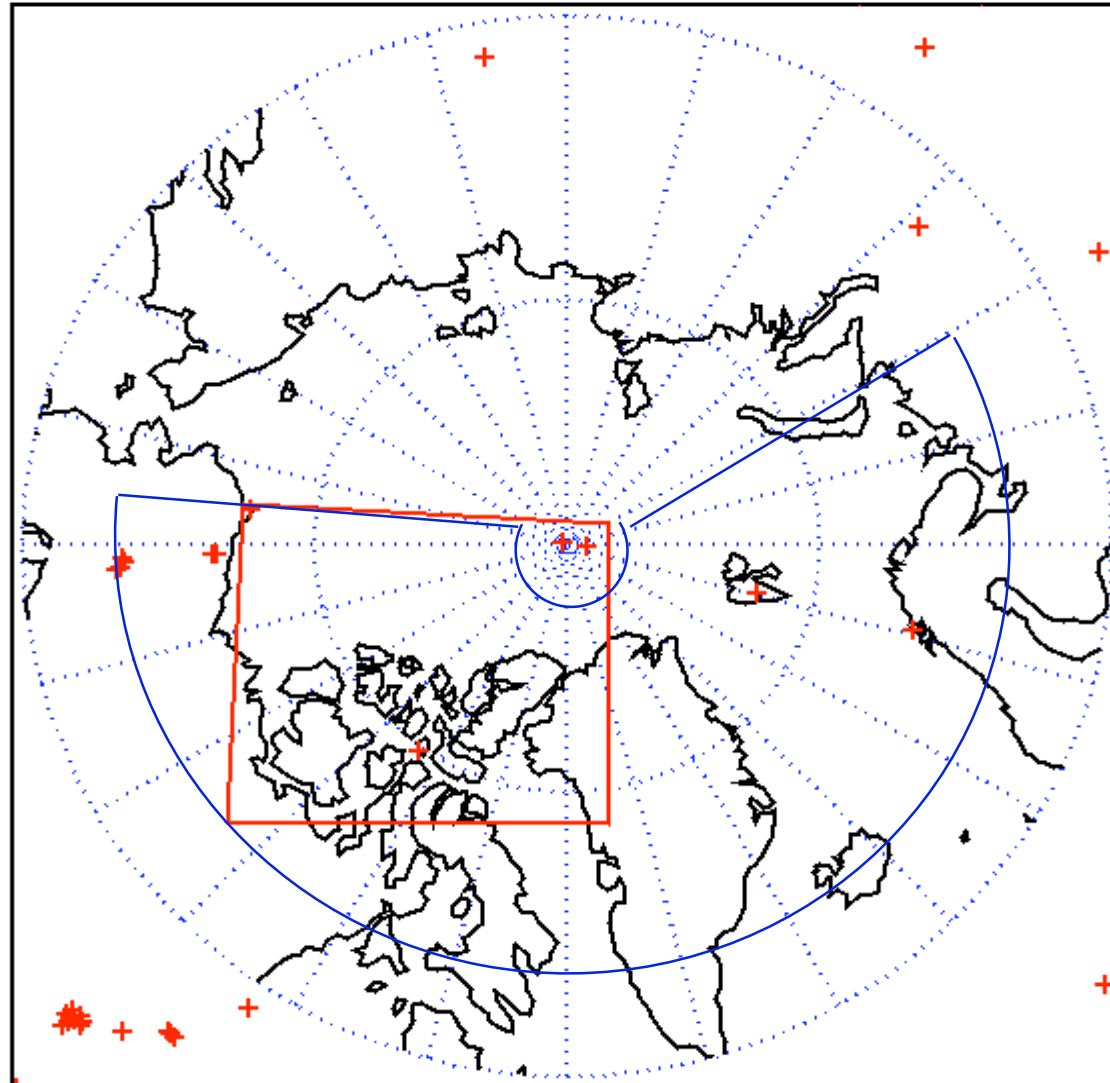
G-polygon vs Bounding box



Example 1:
Bounding box
at low latitudes



GNOMIC, Center=[90, -60]



Example 2: Bounding box
at high latitudes – crossing pole, dateline



An accurate prescreening technique

Definitions and Assumptions:

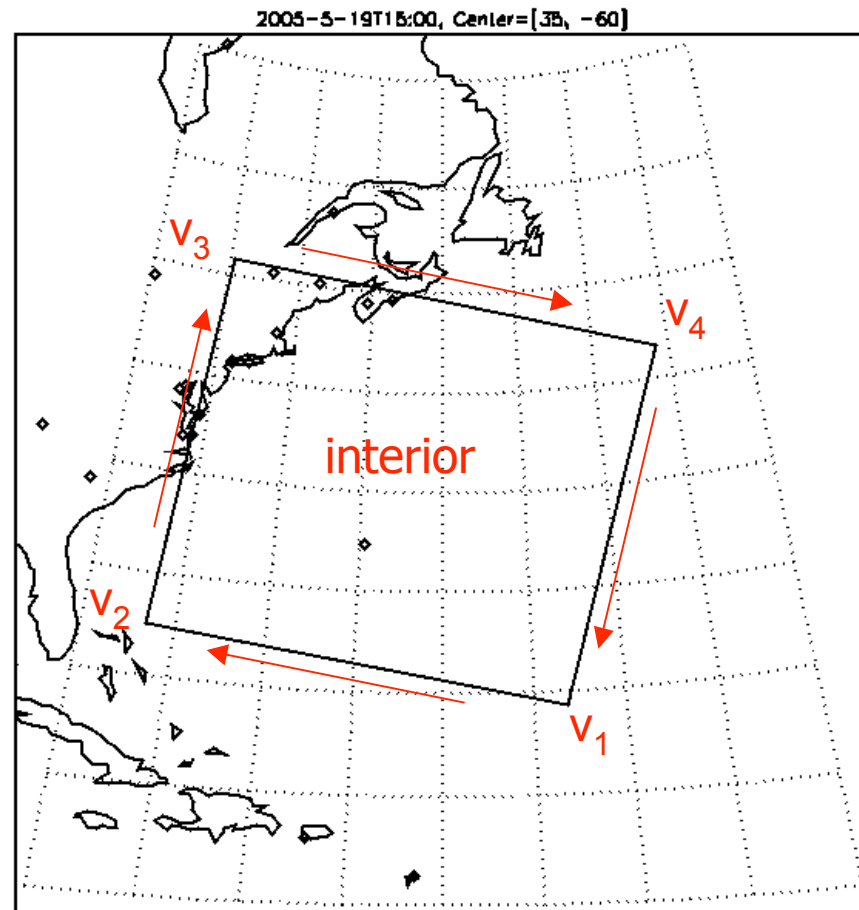
- Earth surface can be approximated by a sphere.
- An AIRS/MODIS granule (6/5 minutes) covers a rectangular region (swath) on the surface of Earth – approximated by **4-sided G-polygon**.
- G-polygon -- polygon on a sphere with **arcs of great circles** as its edges.
- G-polygon divides the sphere into two domains – **interior and exterior**.
- Define the order of vertices of a G-polygon (G-Ring sequence) as follows: when one moves in the order along the boundaries, interior is always on the **right-hand-side**.



G-polygon: interior and exterior

Vertices order (G-ring sequence): 1-2-3-4-1

Clockwise !





Great circle equation

ϕ – longitude, θ – latitude

Great circle equation passing through point $p_1 (\phi_1, \theta_1)$ and $p_2 (\phi_2, \theta_2)$
with a direction from p_1 to p_2 :

$$f(\phi, \theta) = \tan \theta \sin(\phi_1 - \phi_2) + \tan \theta_1 \sin(\phi_2 - \phi) + \tan \theta_2 \sin(\phi - \phi_1) = 0.$$

Great circle divides sphere into three domains :

On great circle: $f(\phi, \theta) = 0$

On right - hand - side : $f(\phi, \theta) > 0$;

On left - hand - side : $f(\phi, \theta) < 0$.



Criterion for G-polygon interior

A swath with 4 corners:

$$v_1(\phi_1, \theta_1), v_2(\phi_2, \theta_2), \\ v_3(\phi_3, \theta_3), v_4(\phi_4, \theta_4).$$

Edges of the swath :

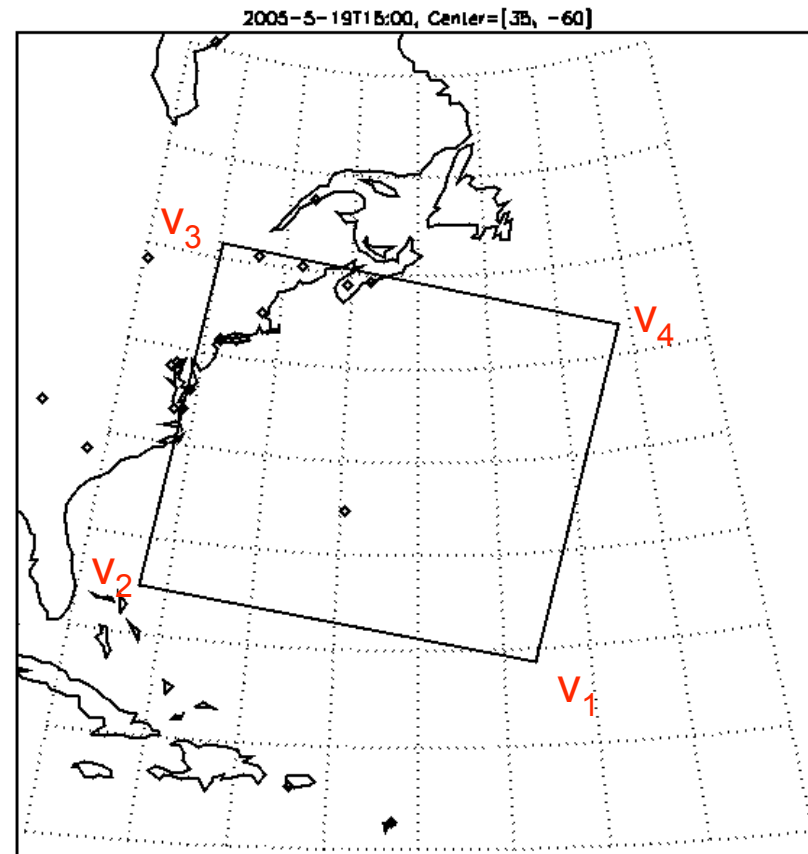
$$f_i(\phi, \theta) = 0, \quad (i = 1, 2, 3, 4)$$

with $(v_1, v_2), (v_2, v_3),$

$(v_3, v_4), (v_4, v_1)$

replacing (p_1, p_2) .

A point (ϕ, θ) is inside swath
if $f_i(\phi, \theta) > 0$ for $i = 1, 2, 3, 4$





Application to AIRS data

Subsetting AIRVBRAD
data for 36 sites in

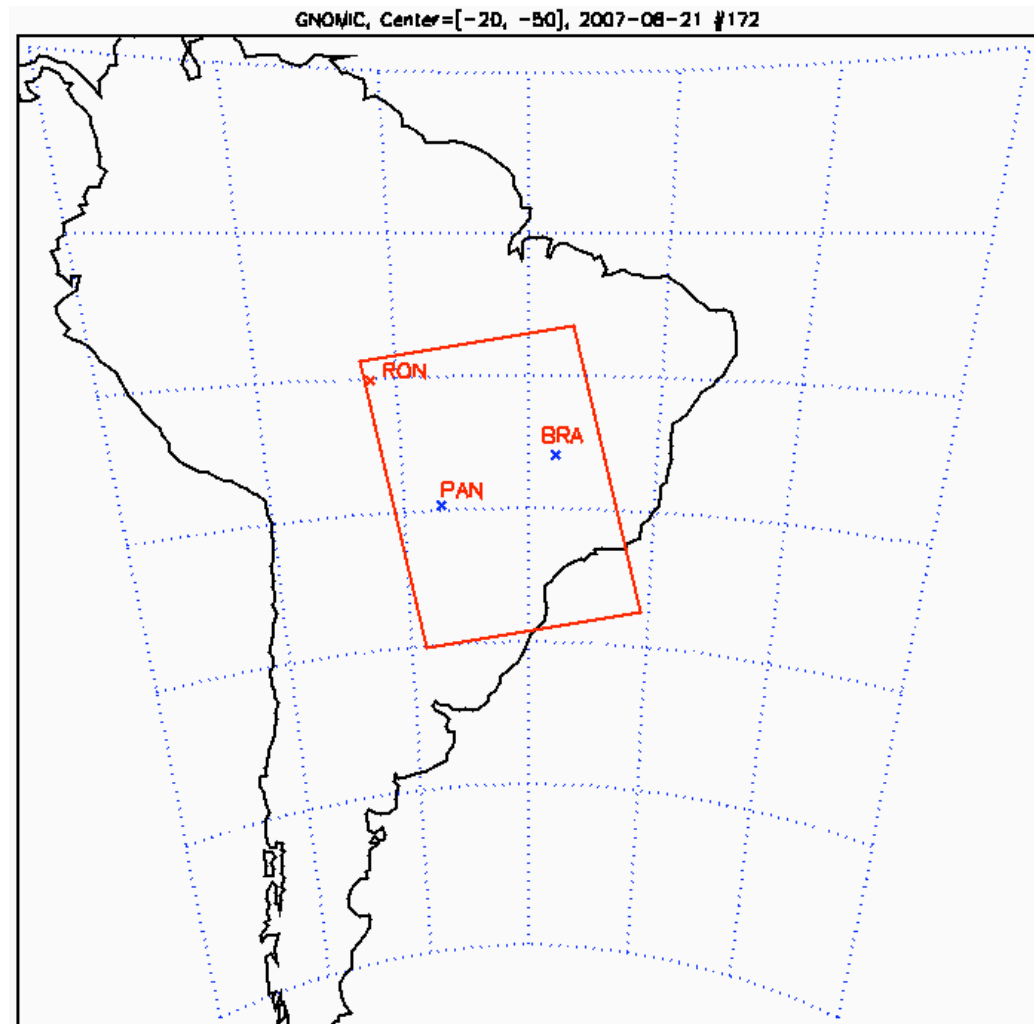
Coordinated Enhanced
Observing Period Data
Management (CEOP)

Site	Lon	Lat
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RON	-61.93	-10.08
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BRA	-47.92	-15.93
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PAN	-57.01	-19.56
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AIRS geolocation information

AIRVBRAD data

Geolocation information:

Longitude, Latitude

135 X 90 (=12150)

Vertices sequence:

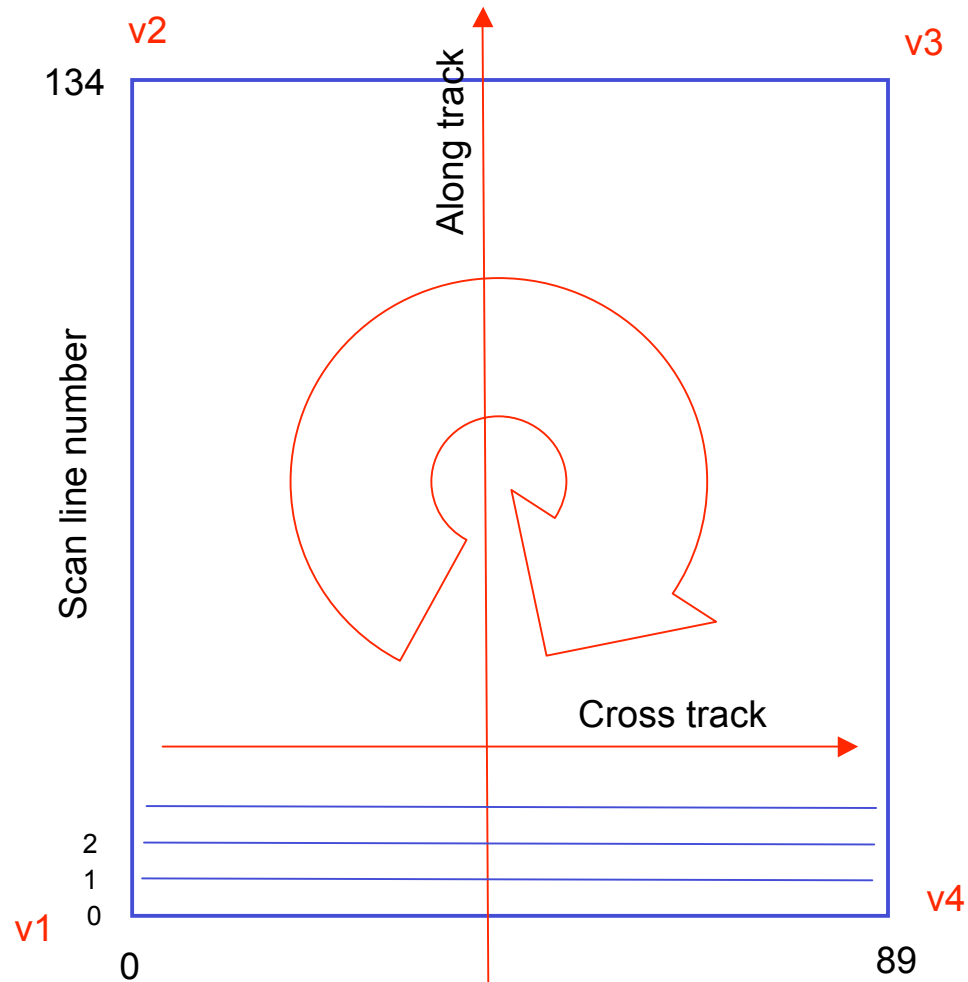
Vertex	2-dim	1-dim
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V1	[0,0]	[0]
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V2	[134, 0]	[12060]
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V3	[134, 89]	[12149]
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V4	[0, 89]	[89]
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Performance

CEOP AIRVBRAD subsetter using G-polygon based prescreening

Test on 406 granules of 2007.08.20, 21, 22

- Before --

Use bounding rectangle plus special treatments for dateline/pole crossing granules. Sometimes need to scan all pixels. Found 130 sites covered.

- After –

Only need to know lat/lon values of the 4 corners and blindly apply the technique. Treat all ground sites and granules equally. Found 131 sites covered.



Performance - accuracy

- Before –

false negative (all marginal):

2007.08.20 #181 PAN

2007.08.21 #074 EIS

2007.08.22 #119 NSA

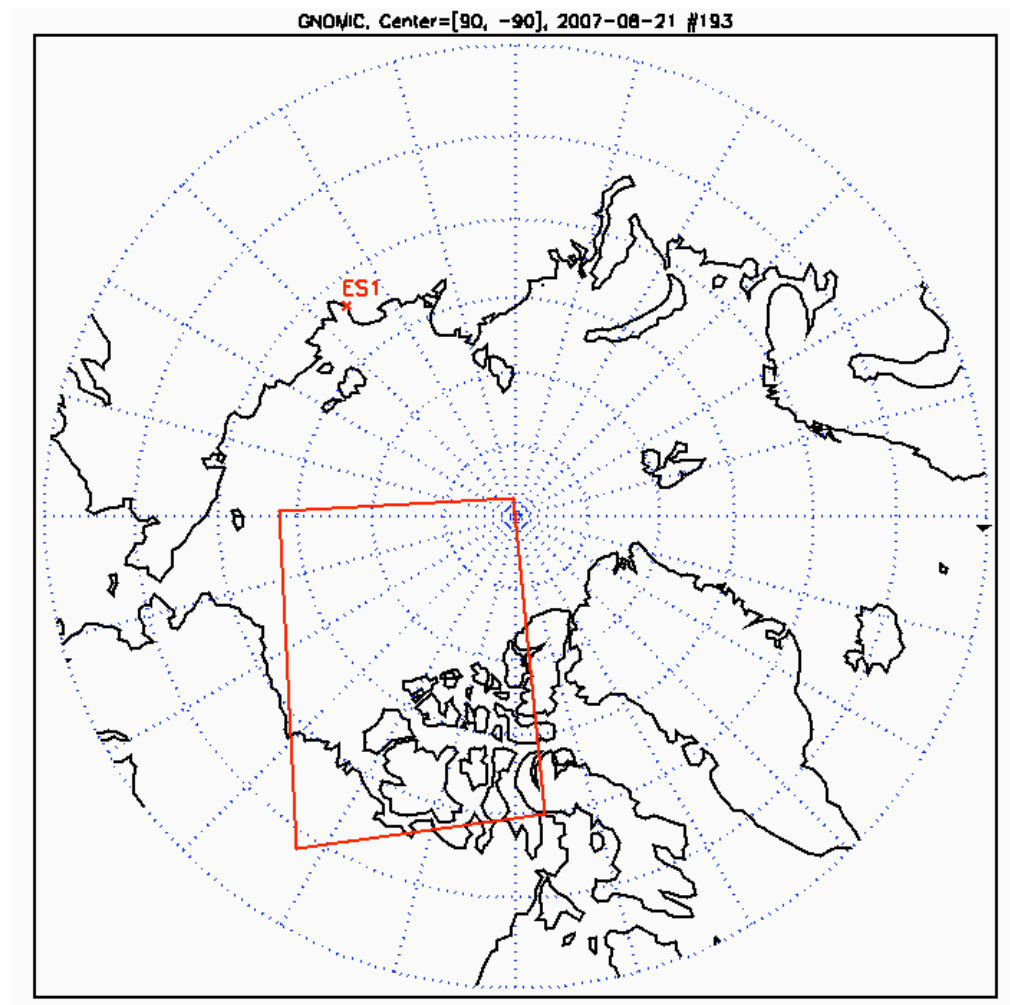
false positive:

2007.08.21 #160 ES1

2007.08.21 #193 ES1

- After --

No false positive, no false negative.





Performance - efficiency

CEOP AIRVBRAD subsetter using G-polygon based prescreening

Test on 406 granules of 2007.08.20, 21, 22

checkSitePos -- function checking if a granule covers any sites

Time profiling results:

- Before --

Computer time: 0.36 sec. 0.17 ms/call

- After –

Computer time: 0.03 sec. 0.01 ms/call

Over 10 times faster!



Conclusion

- Accurate, reliable and efficient pre-screening method.
- Treats all granules, ground sites equally. Can be applied blindly as long as 4 corners are in clockwise order.
- Boundaries can be expanded or shrunk to meet users' special requirement on marginal sites. (see the paper)
- Recommended for Matchup PGEs, V6 planning.